

Lower Bounds for Comparison-Based Sorting Algorithms (Ch. 8)

We have seen several sorting algorithms that run in $\Omega(n \lg n)$ time in the worst case (meaning there is some input on which the algorithms run in *at least* $\Omega(n \lg n)$ time).

- mergesort
- heapsort
- quicksort

In all comparison-based sorting algorithms, the sorted order results *only from comparisons between input elements*.

Is it possible for any comparison-based sorting algorithm to do better?

Lower Bounds for Sorting Algorithms

Theorem: Any comparison-based sort must make $\Omega(n \lg n)$ comparisons in the worst case to sort a sequence of n elements. (Across all comparison-based sorting algorithms, no worst case runs faster than $n \lg n$ time.)

But how do we prove this?

We'll use the *decision tree model* to represent any sorting algorithm and then argue that no matter the algorithm, there is some input that will cause it to run in $\Omega(n \lg n)$ time.

Question: How many ways are there to order n elements? $n!$

Binary tree

Recall that a binary tree is a tree data structure in which each node has at most 2 children, a left child and a right child.

Sources differ, but most authors agree that a full or proper binary tree is one in which every node has 0 or 2 children.

Binary tree height and upper bound on number of leaves

The *height* of a node x is the maximum number of edges on a path from a leaf to x .

Theorem: A proper binary tree (pbt) of height h has at most 2^h leaves.

Basis: a pbt of height 0 has $2^0 = 1$ leaf

Inductive hypothesis: a pbt of height $k \geq 1$ has at most 2^k leaves.

Inductive step: Show a pbt of height $k+1$ has at most 2^{k+1} leaves.

By the IHOP, we know that a pbt of height k has at most 2^k . A pbt of height $k+1$ is a pbt of height k in which one or more leaves has 2 children. So the number of leaves in a pbt of height 2^{k+1} is at most $2(2^k) = 2^{k+1}$ QED

The Decision Tree Model

Given any comparison-based sorting algorithm, we can represent its behavior on an input of size n by a decision tree – a proper binary tree.

A decision tree is a binary tree such that

- each internal node in the decision tree corresponds to one of the comparisons in the algorithm.
- each node represents a comparison of 2 values (e.g., $x : y$) s.t.
 - if $x \leq y$, take left branch, else if $x > y$, take right branch.
- each leaf in the decision tree represents one possible ordering of the input.

⇒ One decision tree exists for each algorithm and input size

The Decision Tree Model

Example: decision tree with $n = 3$, with elements $A[1..3]$ has $3! = 6$ leaves containing 3 numbers sorted in ascending order.

Let the length of the *longest* root to leaf path in this tree be h

- = worst-case number of comparisons
- ≤ worst-case number of operations of algorithm (since other operations only make the algorithm run longer)

The $\Omega(n \lg n)$ Lower Bound

Theorem: Any decision tree for sorting n elements has height $\Omega(n \lg n)$ (therefore, any comparison-based sorting algorithm requires $\Omega(n \lg n)$ comparisons in worst case).

Proof: Let h be the height of the tree. Then we know

- the tree has at least $(\geq) n!$ leaves
- the tree is binary, so it has at most $(\leq) 2^h$ leaves

of leaves is upper bounded by 2^h and lower bounded by $n!$

$$2^h \geq \text{number of leaves} \geq n!$$

so we have:

$$2^h \geq n!$$

taking lg of both sides:

$$\lg(2^h) \geq \lg(n!)$$

$$h \geq \Omega(n \lg n) \text{ (Eq. 3.18)} \quad \square$$

Optimal Sorting Algorithms

- This lower bound proof tells us that heap-sort and merge-sort are asymptotically optimal comparison-based sorting algorithms.
- Randomized-Quick-Sort is asymptotically optimal with high probability.
- insertion-sort, selection-sort, and bubble-sort are not asymptotically optimal comparison-based algorithms.