RECURSIVE ALGORITHMS:

Process for determining running time of iterative algorithms:

- 1. Decide on a parameter indicating input size.
- 2. Identify the algorithm's basic operation.
- 3. Check whether the number of times the basic operation is executed can vary on different inputs of the same size; if it can, the worst-case and best-case efficiencies must be investigated separately.
- 4. Set up a recurrence relation, with an appropriate initial condition, for the number of times the basic operation is executed.
- 5. Solve the recurrence or somehow ascertain the the order of growth of its execution.

A recursive algorithm can often be described by a recurrence equation that describes the overall runtime on a problem of size n in terms of the runtime on smaller inputs.

```
IterativeBinarySearch(A, T):
Input: A is an array of numbers sorted in increasing order
T is the element to find
Output: The index of T or -1 if T not found
  n = A.length
  L = 1
  R = n
  while L \le R
      m = floor((L + R) / 2)
      if T > A[m]:
          L := m + 1
      else if T < A[m]:
          R := m - 1
      else:
          return m
  return -1
```

Ask: What is basic operation? Are there b-c and w-c running times? If so, give instances of each. Express running time in asymptotic notation.

```
RecursiveBinarySearch(A, left, right, x):
{
      // Base condition 1 (search space is exhausted)
      if (left > right) {
          return -1;
      }
      // we find the mid value in the search space and
      // compare it with key value
      int mid = (left + right) / 2;
      // Base condition 2 (key value is found)
      if (x == A[mid]) {
          return mid;
      }
      // Recursive condition 1
      // discard all elements in the right search space including the mid element
      else if (x < A[mid]) {
          return binarySearch(A, left, mid - 1, x);
      }
      // Recursive condition 2
      // discard all elements in the left search space
      // including the mid element
      else {
          return binarySearch(A, mid + 1, right, x);
      }
}
 For divide and conquer algorithms, we get recurrences like:
        = \Theta(1) if n < c or
           aT(\frac{n}{h}) + D(n) + C(n) otherwise
 where
            number of subproblems we divide the problem into
            size of subproblems (in terms of n)
            time to divide the size n problems into subproblems
  C(n) = time to combine the subproblem solutions to get answer for size n
```

What is T(n) for BinarySearch?

Go to slides for MergeSort.

NEXT SUBJECT: Heap-Sort (Chapter 6)